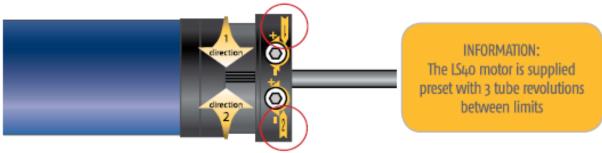
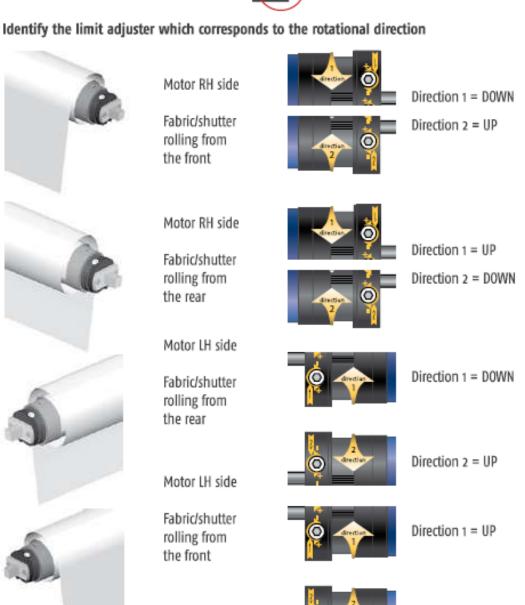
WT Motor Hardwired

Limit Setting

1. Identifying the Correct Limit Adjuster



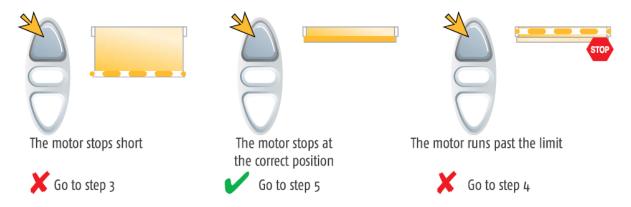




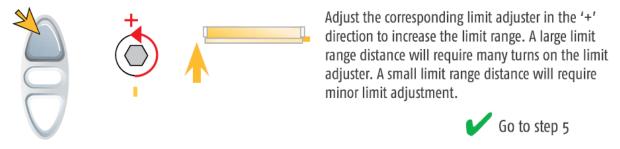
Direction 2 = DOWN

Note: It is advised not to use a drill to set progressive limit settings

2. Top Limit Position - 3 Potential Scenarios

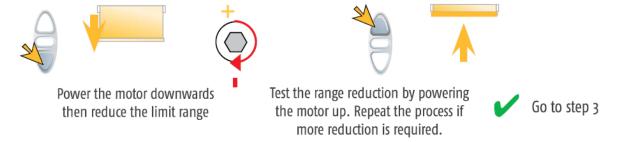


3. Increase the Limit Range at the Top Limit Position while giving an Up Command

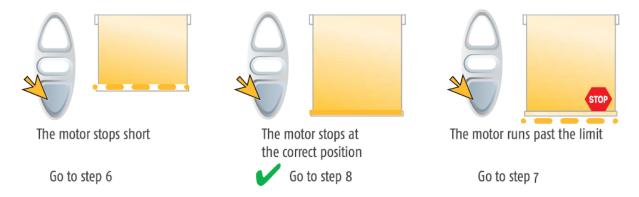


4. Decrease the Limit Range at the Top Limit Position

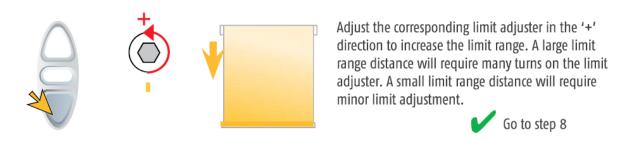
Give a down command to send the motor to approx 300mm from the desired top limit. Turn the corresponding limit adjuster in a clockwise direction (towards '-') for approx. 20 turns. give the up command. If the motor does not stop before the desired limit then repeat until the limit is found.



5. Bottom Limit Position - 3 Potential Scenarios

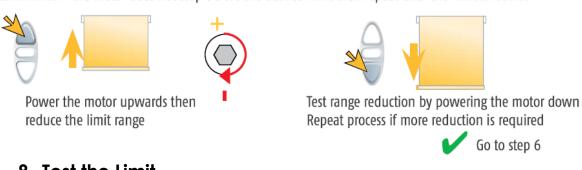


6. Increase the Limit Range at the Bottom Limit Position while giving a Down Command



7. Decrease the Limit Range at the Bottom Limit Position

Give an up command to send the motor to approx 300mm from the desired bottom limit. Turn the corresponding limit adjuster in a clockwise direction (towards '-') for approx. 20 turns. Give the down command. If the motor does not stop before the desired limit then repeat until the limit is found.



8. Test the Limit





Flowchart for Limit Setting

